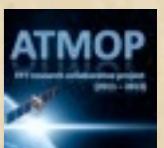


Sunspot data analysis using coherency

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with special thanks to Laure Lefèvre and Fédéric Clette

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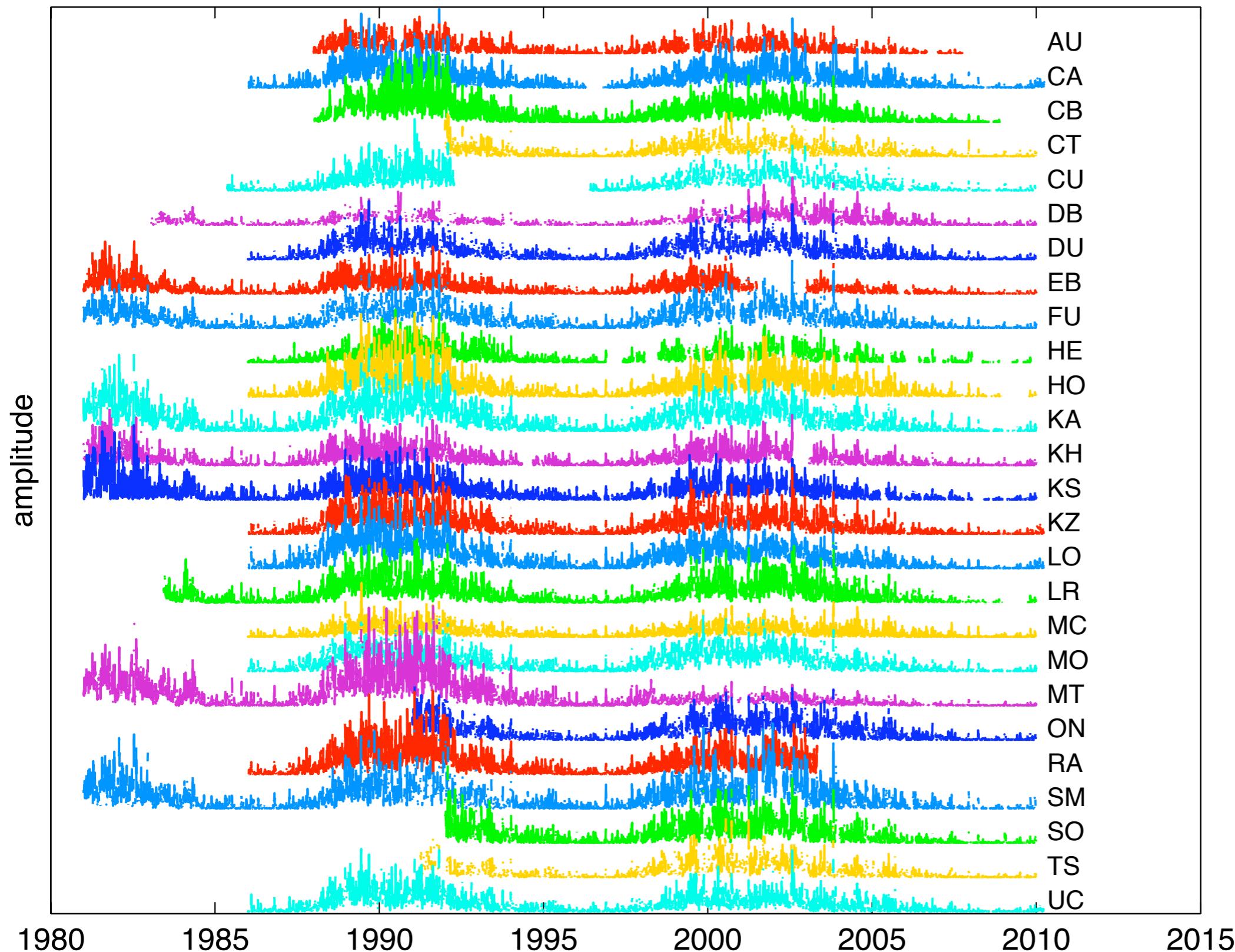
2 questions

- Data gaps are omnipresent in sunspot records :
 - *Fill them self-consistently to have unbiased statistics ?*

- All solar proxies exhibit the same dynamics :
 - *Do the International & Group sunspot numbers really describe the same physics ?*
 - *How are they related to other solar proxies ?*

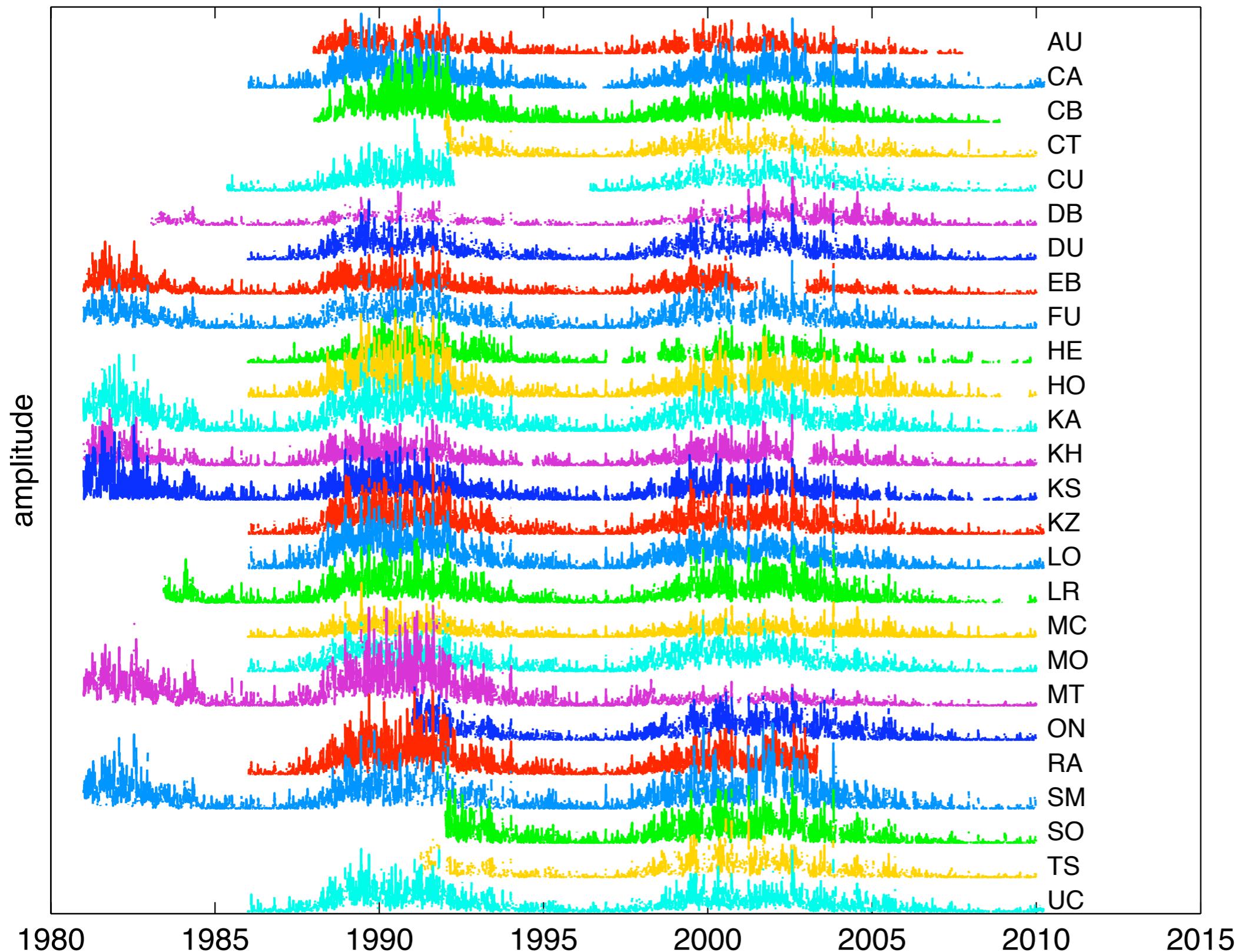
Raw sunspot data

raw data



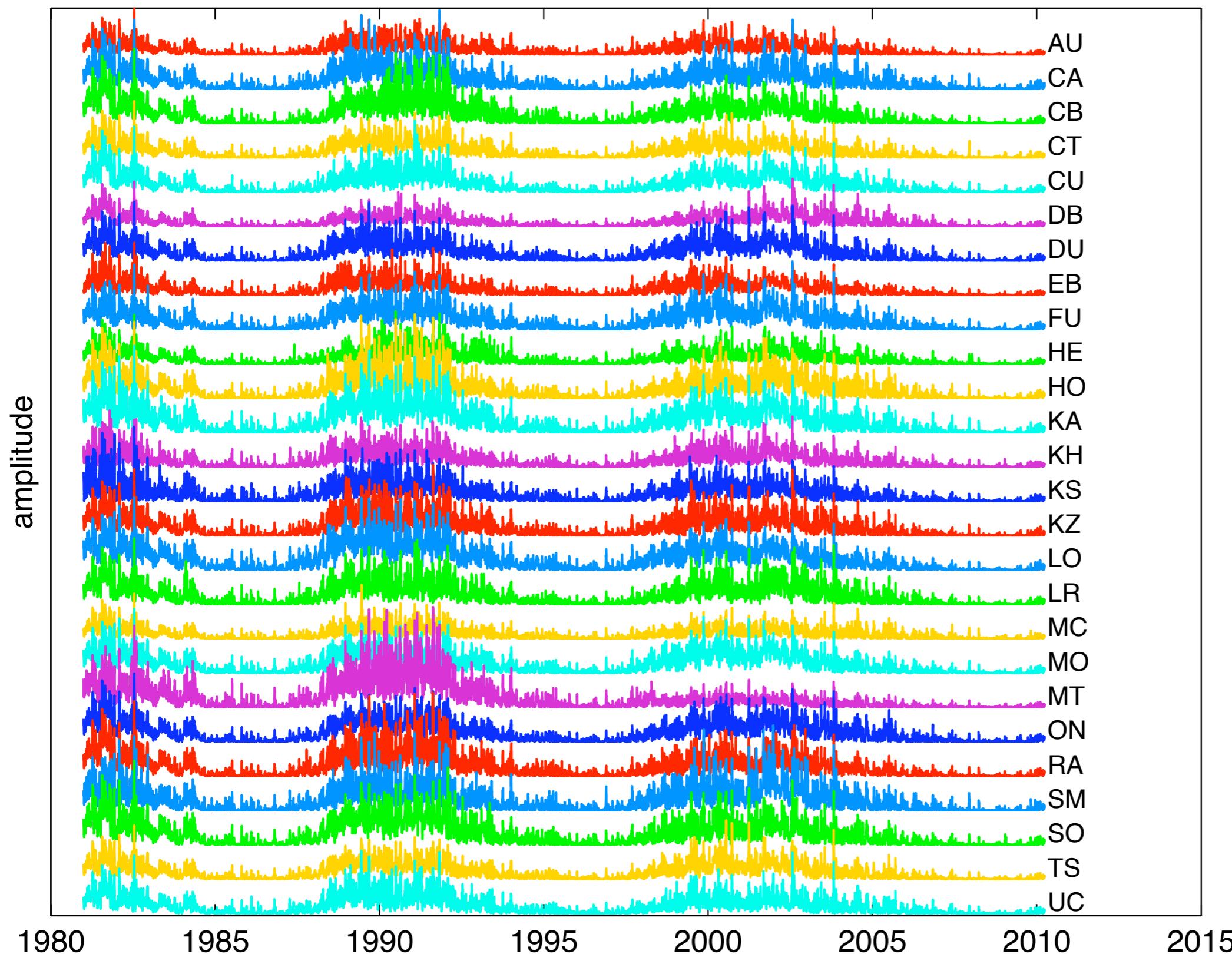
What we would like to have

raw data



What we would like to have

reconstructed data



Our model: coherency

- Assumption: all records describe the same observable

$$SSN(t, k) = S_0(k) + A_1(t) \cdot S_1(k)$$

station Nr

station-dependent offset

“true sunspot number”

station-dependent gain

The diagram shows the equation $SSN(t, k) = S_0(k) + A_1(t) \cdot S_1(k)$. Four arrows point from text labels to specific parts of the equation: a green arrow from "station Nr" points to the term $S_0(k)$; a green arrow from "station-dependent offset" points to the term $A_1(t)$; a blue arrow from "“true sunspot number”" points to the term $S_1(k)$; and a green arrow from "station-dependent gain" points to the product $A_1(t) \cdot S_1(k)$.

Our model: coherency

- Add first order correction to account for discrepancies

$$SSN(t, k) = S_0(k) + A_1(t) \cdot S_1(k) + A_2(t) \cdot S_2(k)$$

- Add more higher order (= small) corrections if needed

$$SSN(t, k) = S_0(k) + \sum_i A_i(t) \cdot S_i(k)$$

Our model: coherency

$$SSN(t, k) = S_0(k) + \sum_i A_i(t) \cdot S_i(k)$$

- The *amplitudes* $A_i(t)$ and *sources* $S_i(k)$ are estimated by Singular Value Decomposition (SVD)
 - similar to principal component analysis
- Data gaps are filled by using the first dominant terms
 - this is done iteratively, see [Dudok de Wit, A&A 533 (2011)]
 - a multiscale approach is used
 - validation by bootstrapping

Our model: coherency

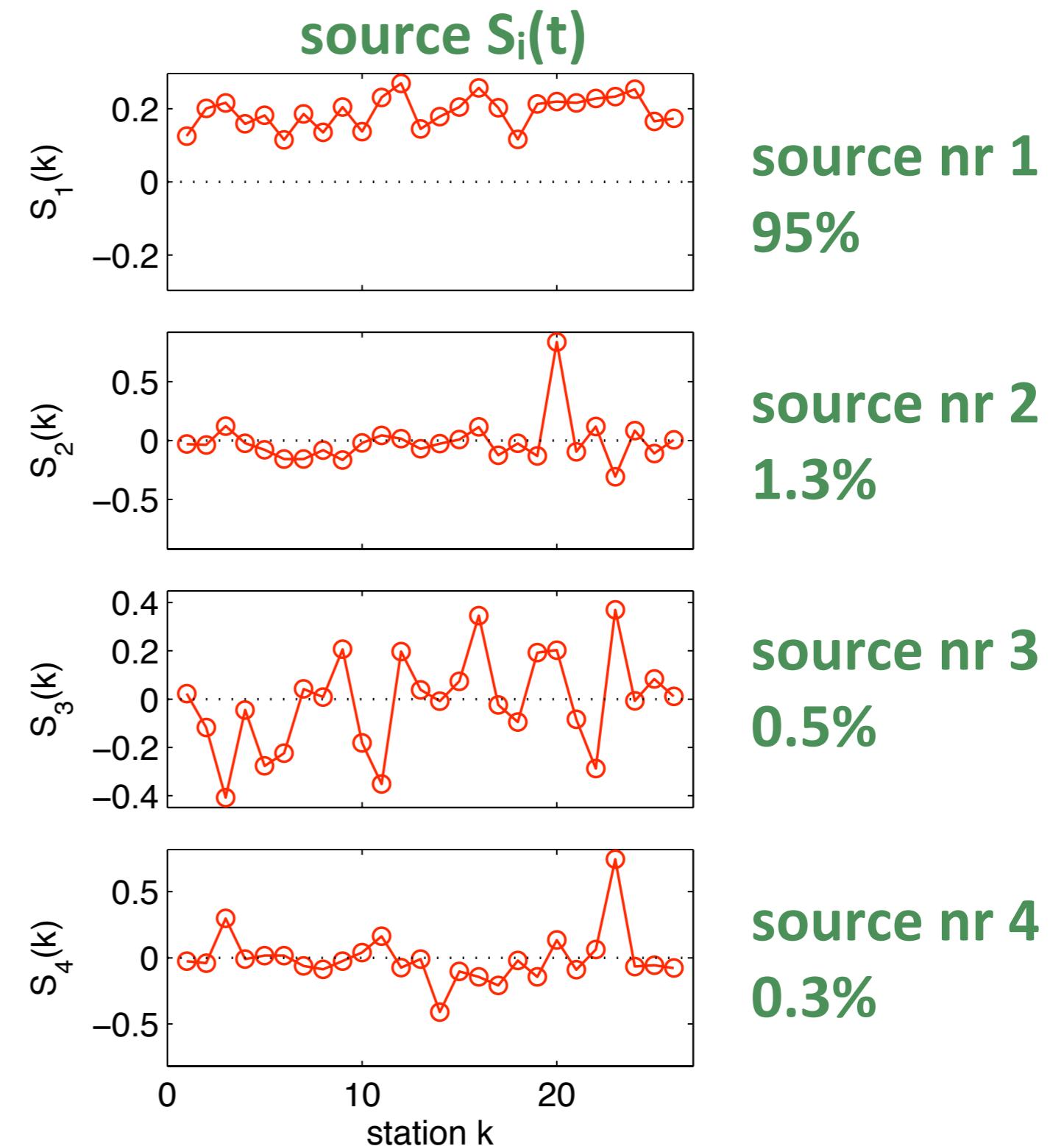
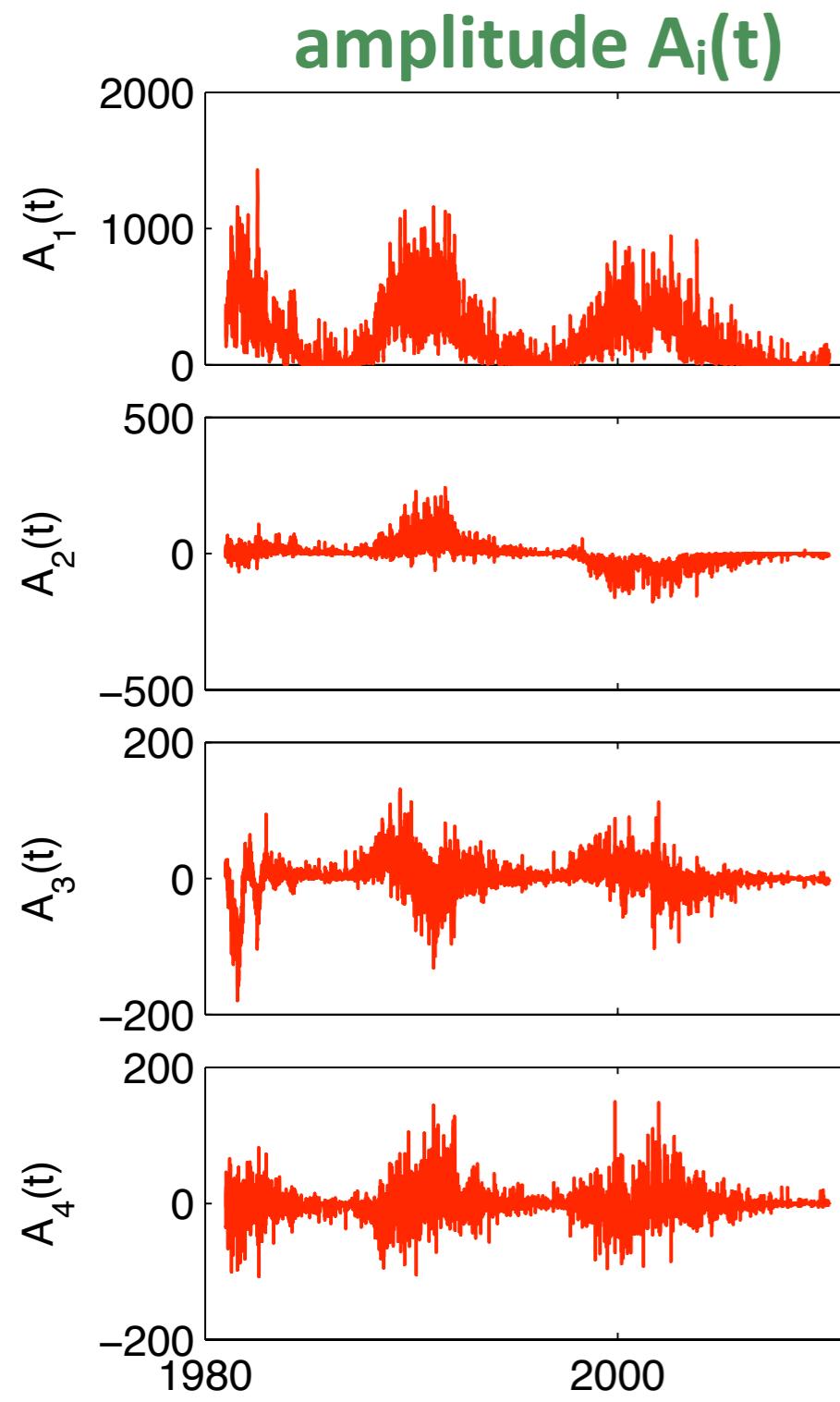
$$SSN(t, k) = S_0(k) + \sum_i A_i(t) \cdot S_i(k)$$

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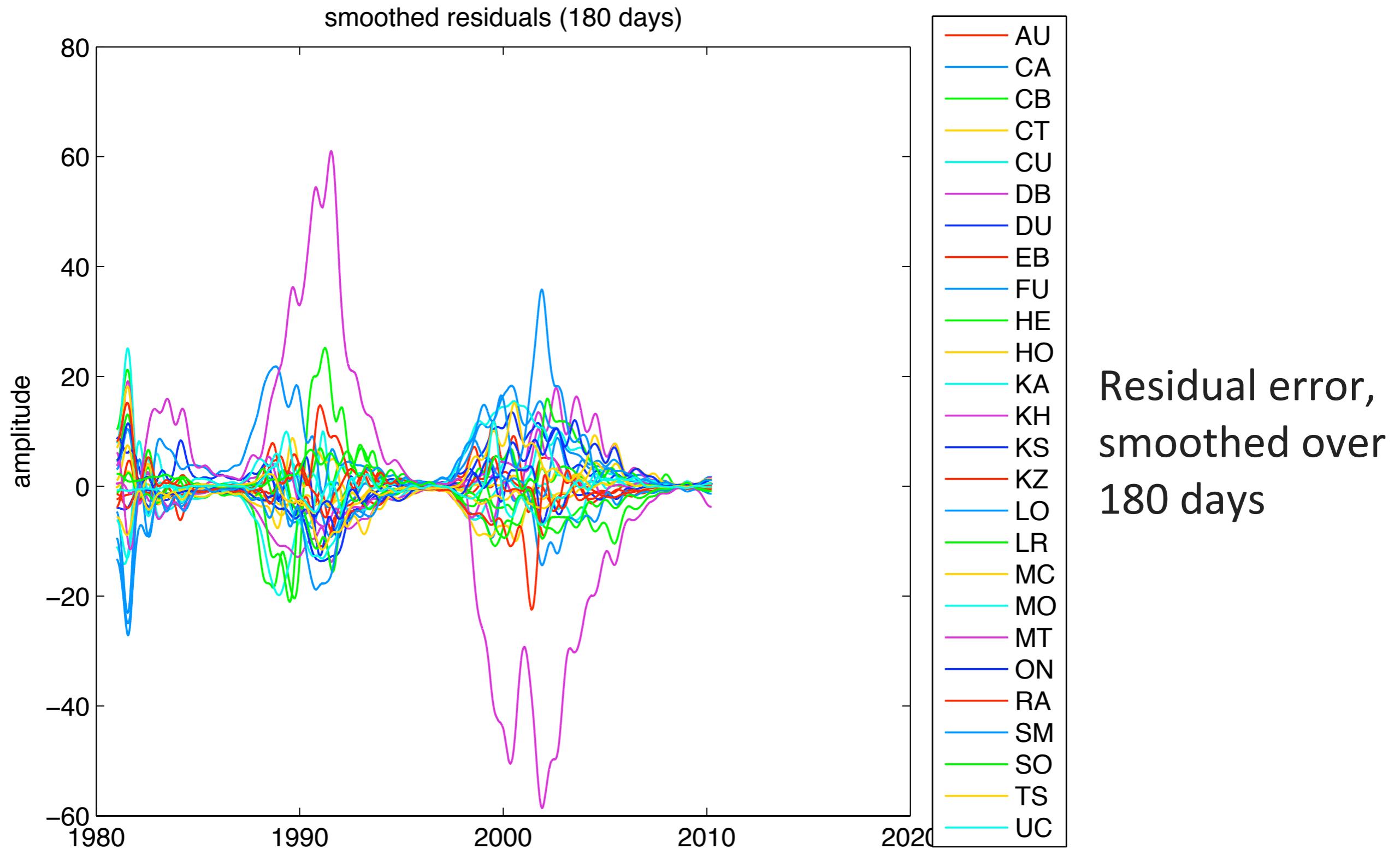
Gaps are filled while ensuring that their statistical properties vs all the other variables remain unaffected

The dominant source terms

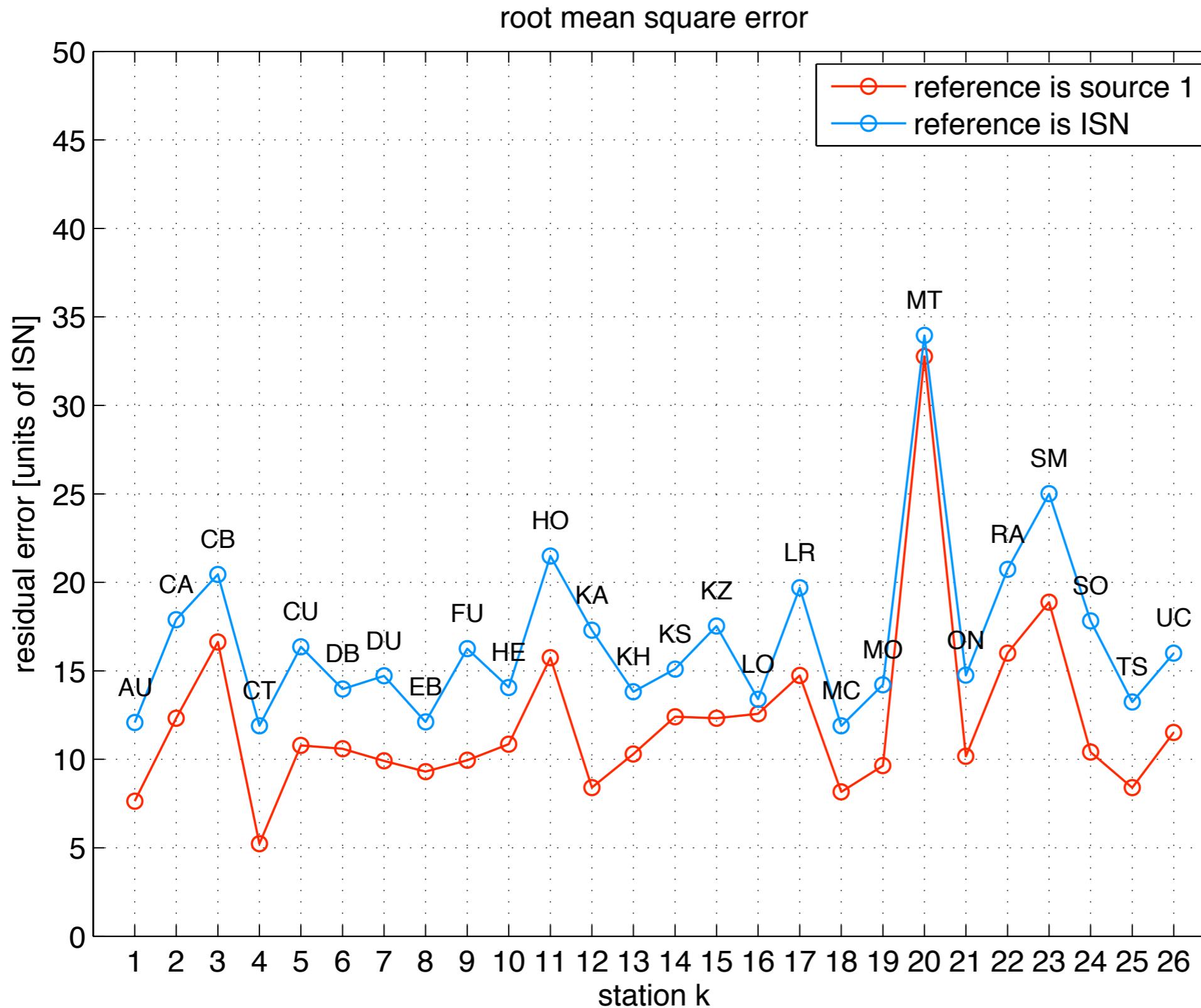
$$SSN(t, k) = S_0(k) + \sum_i A_i(t) \cdot S_i(k)$$



Residual error for each station



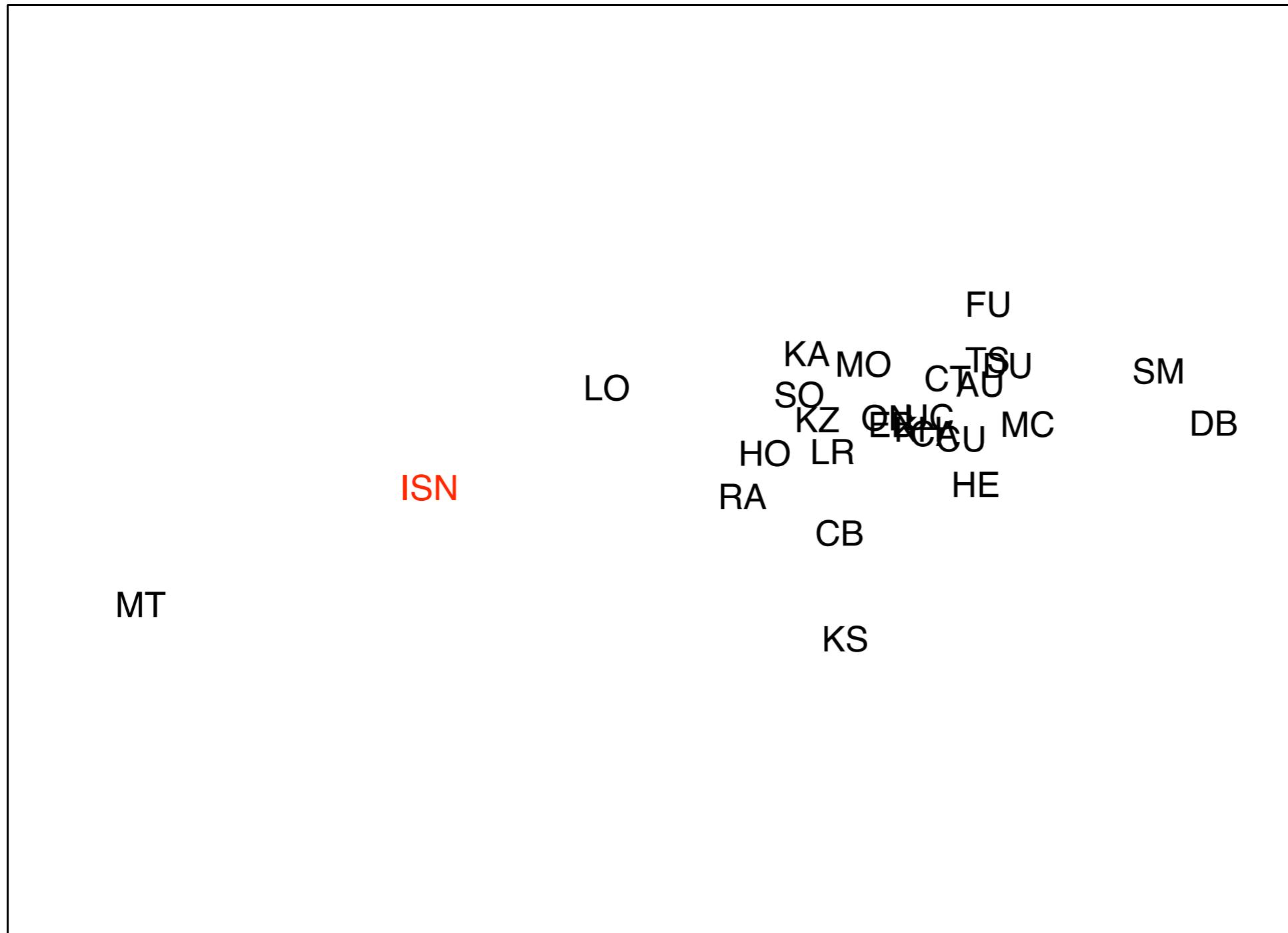
Residual error for each station



**Can't we find a more global
representation of all this ?**

Similarity map

scale=32 days

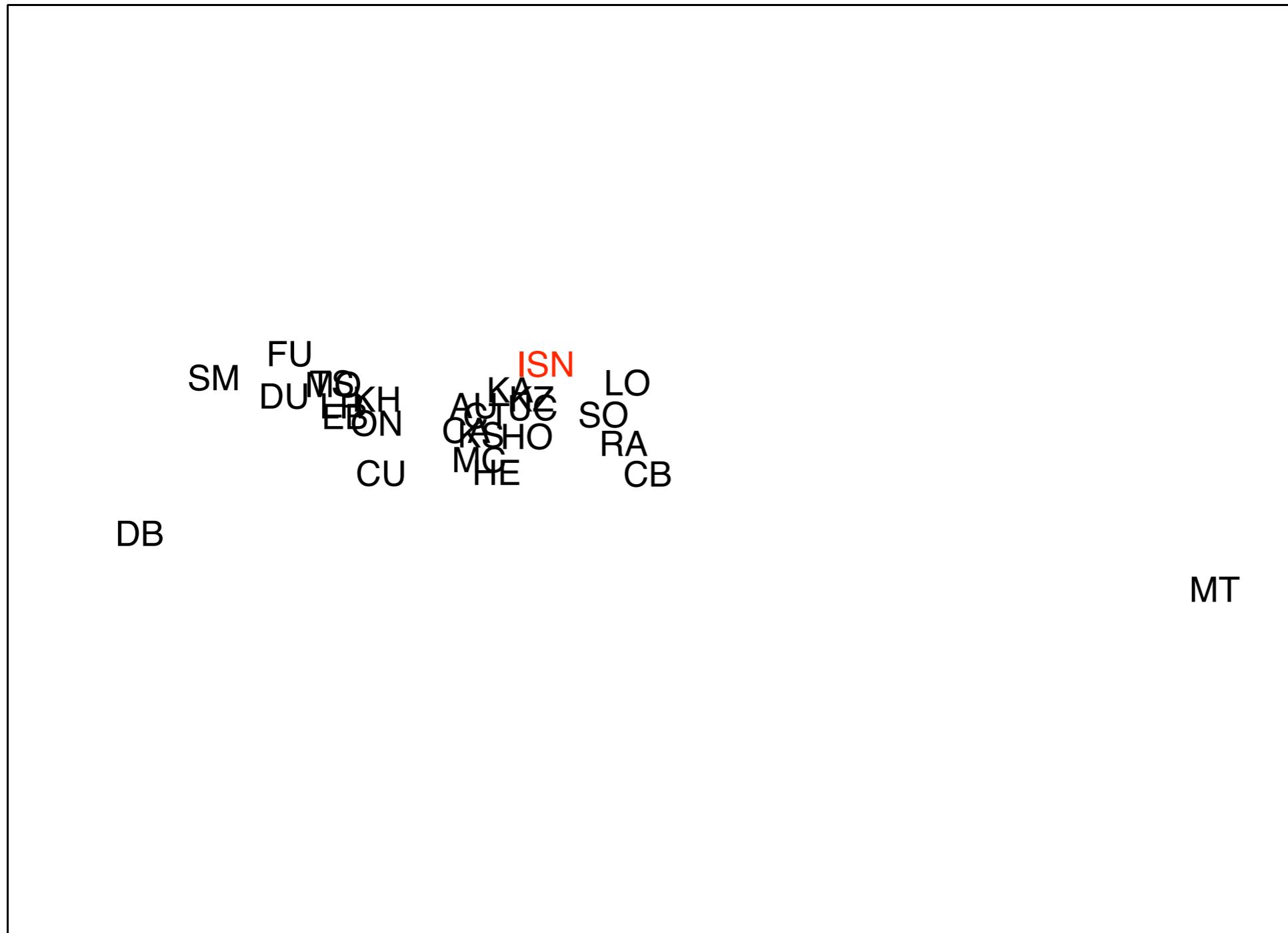


**Solar rotation
time scales**

The distance
between
stations reflects
their degree of
similarity

Similarity map

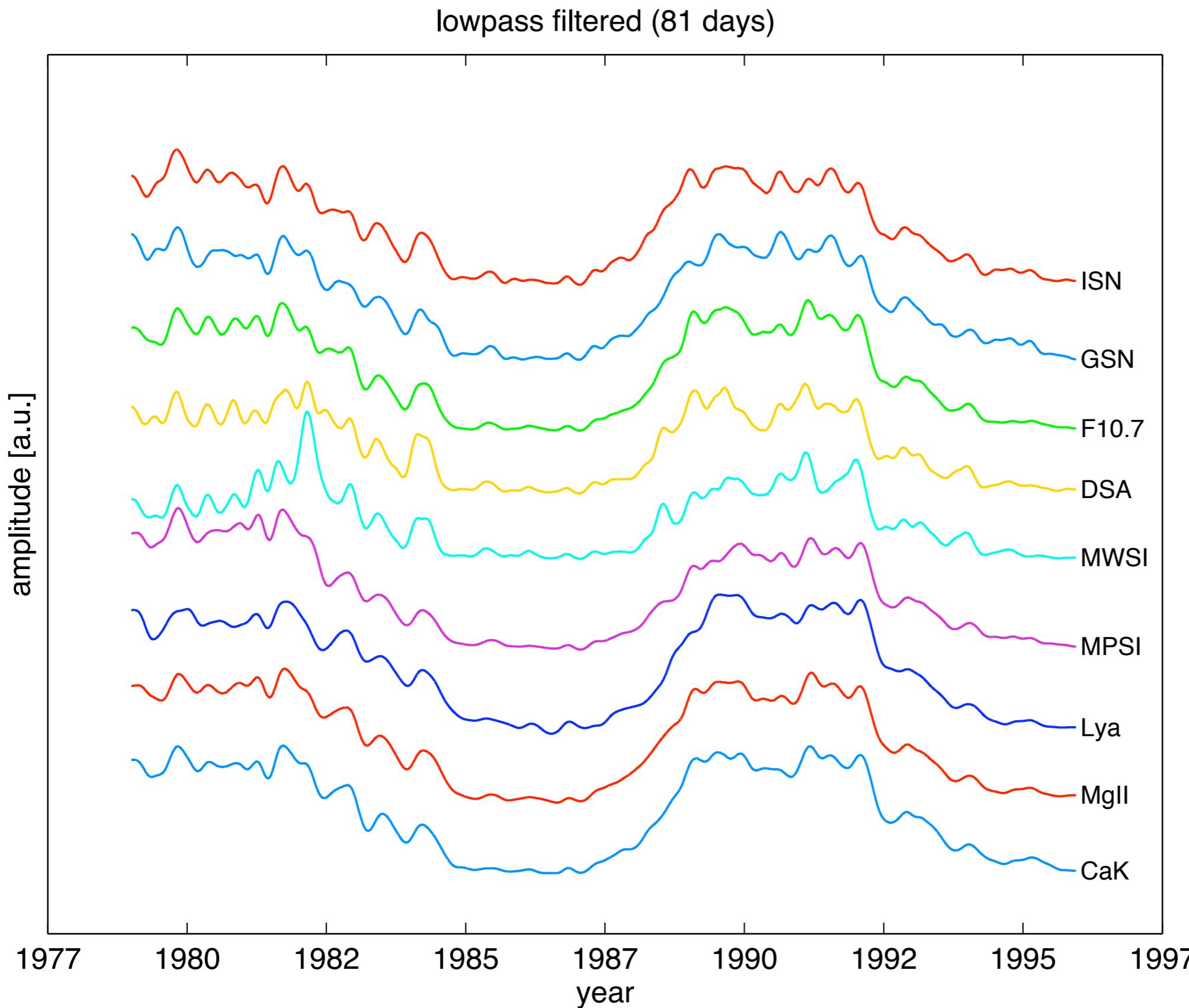
scale > 256 days



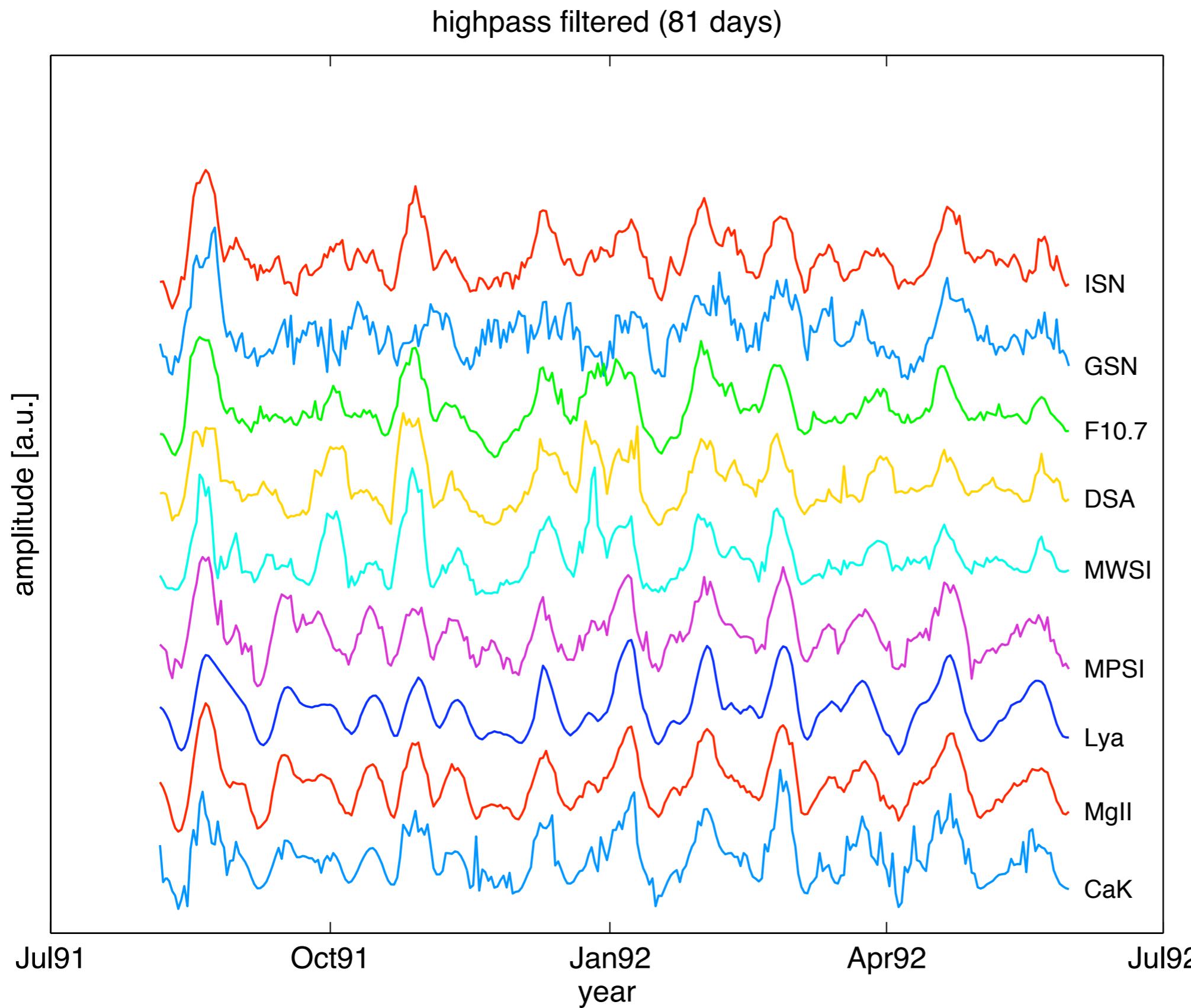
Solar cycle time scales

Comparing the Group SN and the International SN

All solar proxies exhibit strong similarities



All solar proxies exhibit strong similarities

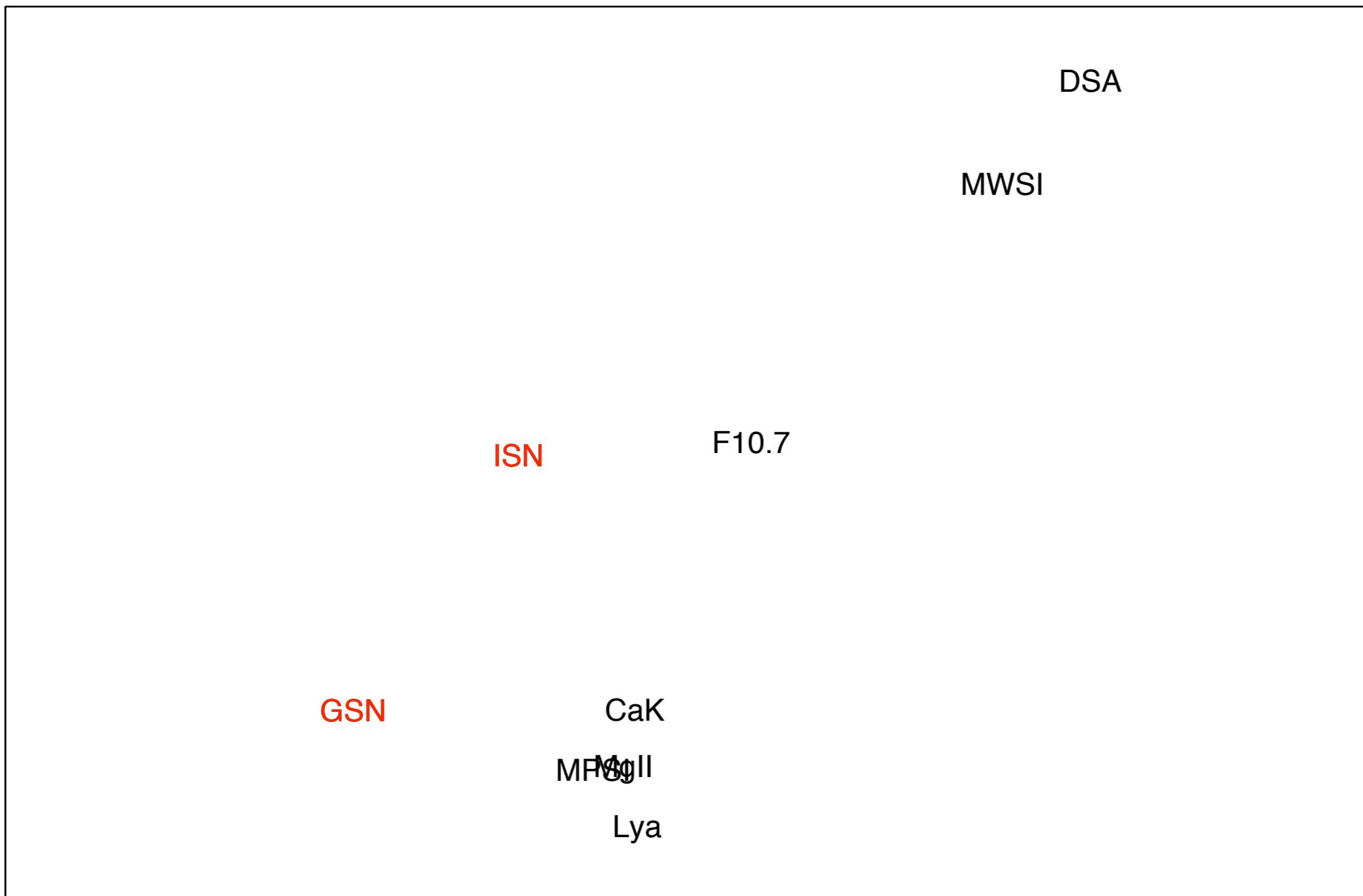


Method

- We use the same method as before, see [Dudok de Wit et al., GRL 36 (2009)]
- All proxies are displayed on a 2D map so that their distance reflects their similarity
 - done separately for each time scale (rotational/cycle)

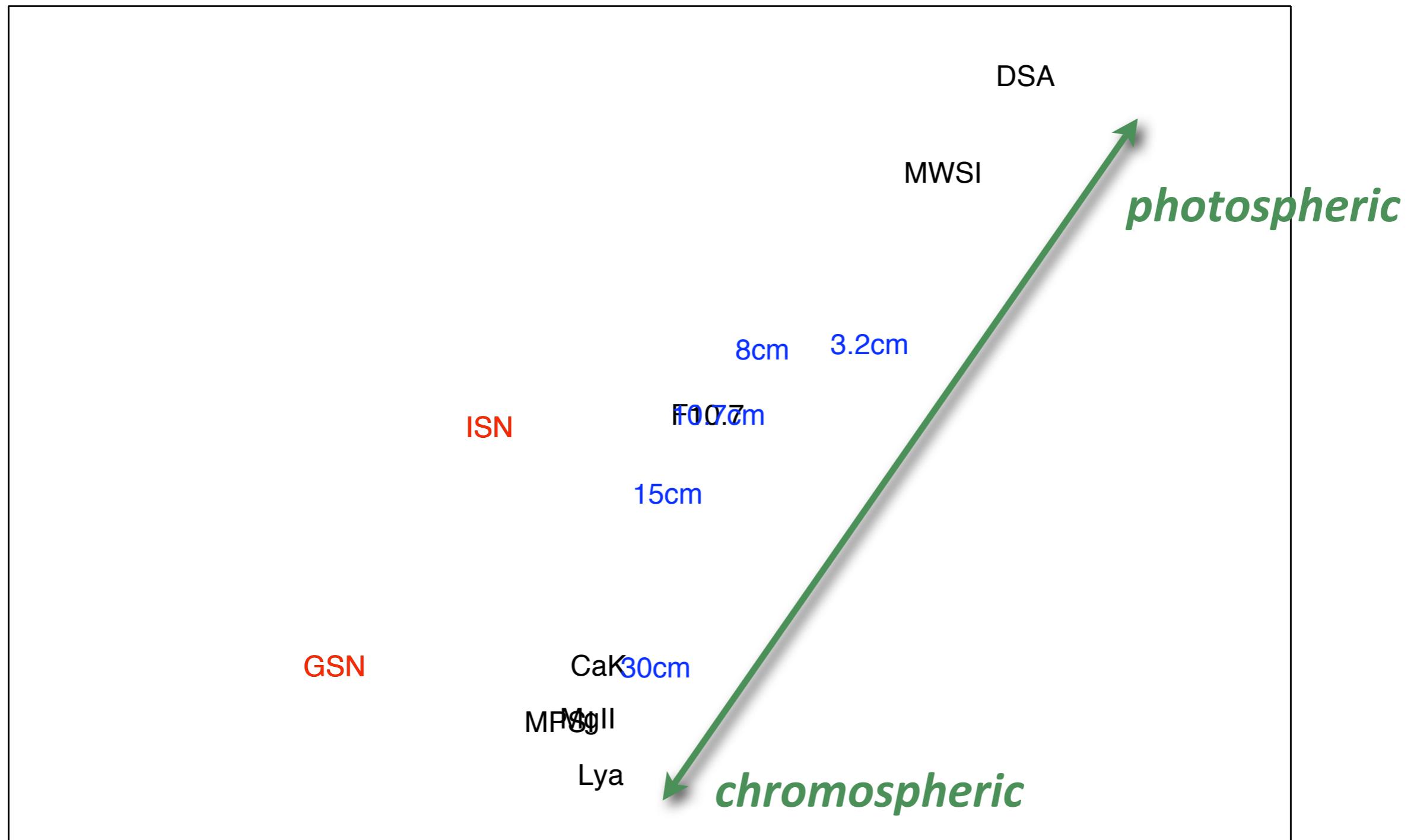
Similarity map: solar rotation scales

scale=32 days



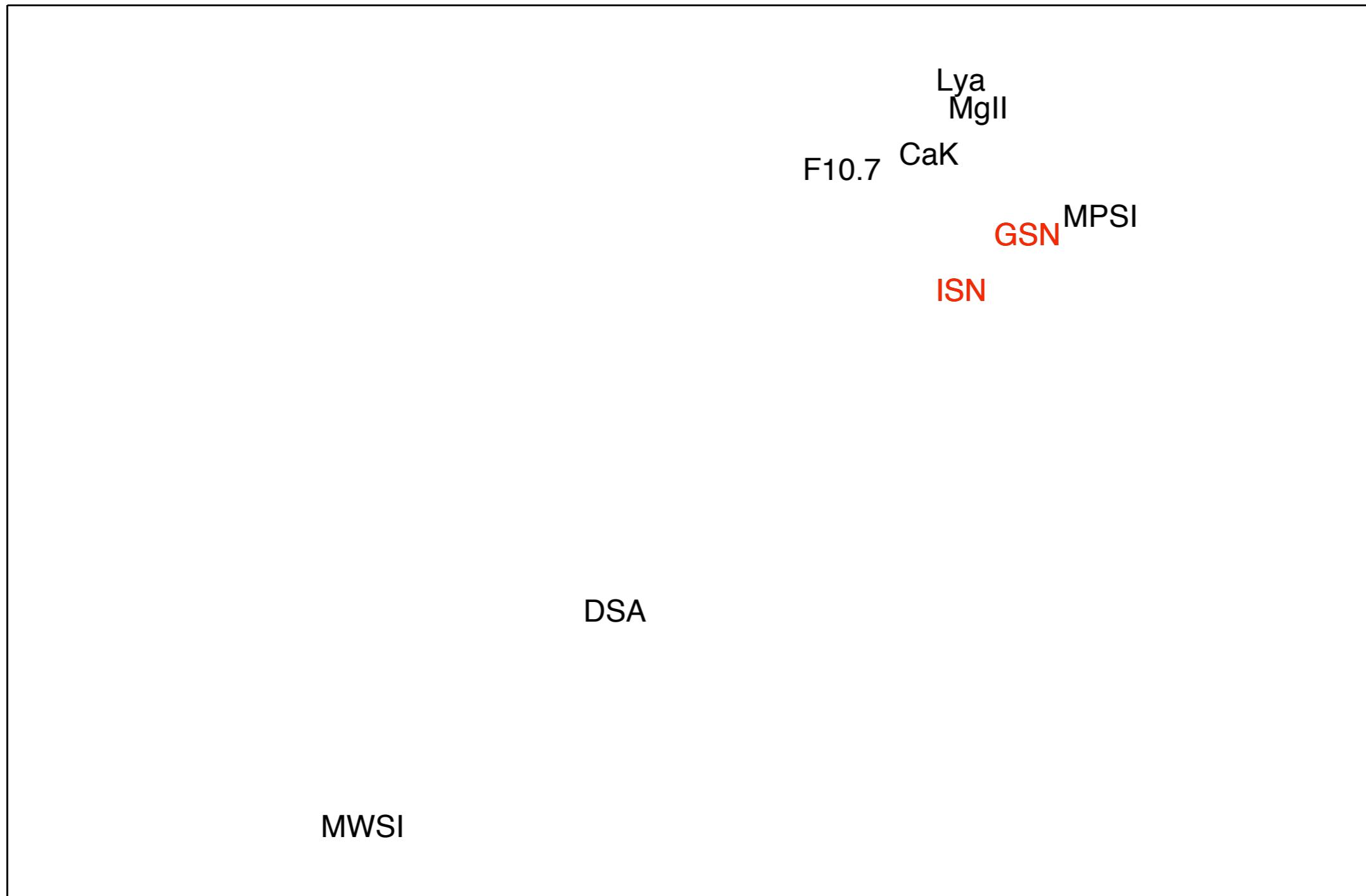
Similarity map: solar rotation scales

scale=32 days



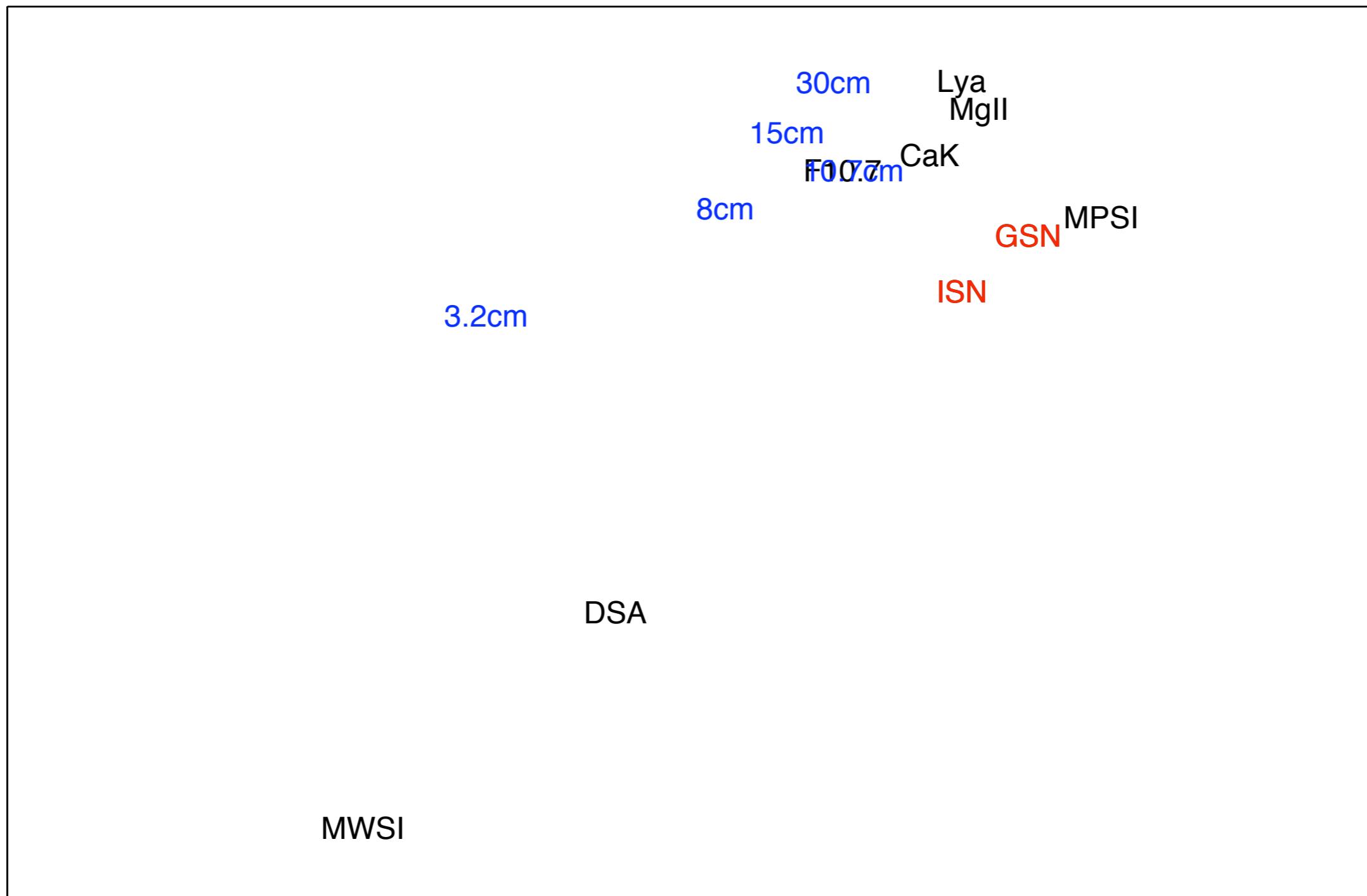
Similarity map: solar cycle scales

scale > 128 days



Similarity map: solar cycle scales

scale > 128 days



Conclusions

- Focus on **commonalities** (or discrepancies) between different stations/proxies
- The ISN and GSN do not describe the same physics as other solar proxies
- The similarity between these proxies is scale-dependent
 - good agreement on medium time-scales does not imply good agreement on long time-scales!
- Multi-wavelength radio observations are a boon

Smoothed sunspot numbers

